1	<u>CL</u>	AIMS

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2	1.	A camera comprising:
3		optics;
4		an image storage medium; and
5		a microprocessor that determines and records the location where an image
6	or a se	eries of images is taken on or in the storage medium.
6 7 8	2.	The camera of claim 1, wherein the storage medium is an emulsion type
::	film, and	wherein the location is imprinted on the film.
9	3.	The camera of claim 2, wherein the microprocessor further records
10	informati	on regarding the exposure of the photo and date of the photo on or in the
1	storage m	nedium.
12	4.	The camera of claim 2, wherein the location is imprinted in the image.
13	5.	The camera of claim 2, wherein the location is imprinted outside of the
14	image.	
15	6.	The camera of claim 3, wherein the exposure information comprises, the
16	aperture	setting, the shutter speed, the film speed.
17	7	. The camera of claim 6, wherein the exposure information further
18	comprise	es metering information such as aperture priority, shutter priority, or under or
19	over exp	osure settings of +/- f stops.
20	. 8	. The camera of claim 1, wherein the image is stored in the storage medium
21	in a digit	al format.

9. The camera of claim 8, wherein the storage medium is solid state memory.

23	10. The camera of claim 8, wherein the storage medium is an optical disk.
24	11. The camera of claim 9, wherein the solid state memory is contained in a
25	removable memory card.
26	12 The camera of claim 8, wherein the storage medium is flash type
27	memory.
28	13. The camera of claim 1, wherein the location is determined for each image
<b>2</b> 9	recorded.
28 29 30	14. The camera of claim 1, wherein the location is determined for a series of
<del>-</del> 31	images.
<b>3</b> 2	15. The camera of claim 1, wherein the location information comprises
<u>1</u> 33	geographic coordinates.
133 134	16. The camera of claim 1, wherein the location information comprises the
35	name of the city, state, country, province, or locale where the image was taken.
36	17. The camera of claim 1, wherein microprocessor controlled system
37	comprises a global positioning system.
38	18. The camera of claim 1, wherein the microprocessor controlled system
39	comprises a cellular transceiver.
40	19. A method for determining and recording the location of an image
41	comprising:
42	capturing and recording the image on a storage medium with a camera;
43	determining the location where the image was captured with said camera; and

44	recording the location where the image was captured on the storage medium, such that
45	the image and the location are correlated.
46	20. The method of claim 19, further comprising manipulating the images and
47	locations into a travel log.
48	21. The method of claim 19, wherein the storage medium is flash memory.
<b>4</b> 9	22. The method of claim 19, wherein the storage medium is an emulsion type
<b>4</b> 9 <b>5</b> 0	$_{ m film}.$
<b>5</b> 1	23. The method of claim 19 wherein determining the location comprises
<b>5</b> 2	communicating with global positioning satellites via a global positioning receiver.
53 54 55 55	24. The method of claim 19 wherein determining the location comprises
<b>15</b> 4	triangulating the location of the camera via a cellular transceiver.
55	25. The method of claim 23 wherein determining the location comprises
56	triangulating the location of the camera via a cellular transceiver.
57	26. The method of claim 23 wherein the location is determined for each image
58	recorded by the camera.
59	27. The method of claim 23 wherein the location is determined when prompted
60	by a user of the camera.
61	28. The method of claim 27, wherein the prompting is triggered by taking of the
62	image or by a separate command issued by the user.
63	29. The method of claim 23, wherein triangulating the location of the camera

comprises usage of a cellular control channel.

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- 30. The method of claim 19, wherein the image location is recorded in or near the image frame.
  - 31. The method of claim 19 further comprising recording exposure information for each image recorded.
    - 32. The method of claim 19 wherein determining the location comprises determining the geographic coordinates of the location.
    - 33. The method of claim 32 further comprising correlating the geographic coordinates with the name of the location.
      - 34. A camera for capturing an image comprising:

        optical lens means for capturing an optical image;

        means for recording the optical image onto a storage medium;

        means for determining the location where the optical image was captured; and means for recording the location onto the storage medium.
    - 35. The camera of claim 34 wherein the means for recording the optical image records a digital image, and wherein the storage medium is a flash memory card.
    - 36. The camera of claim 34 wherein the means for determining the location comprises a GPS receiver that determines the position of the camera when the image is captured.
    - 37. The camera of claim 34 wherein the means for the determining the location comprises a cellular transceiver that triangulates the position of the camera when the image is captured.

85	38. The camera of claim 34 wherein the means for recording the location
86	comprises and optical mechanism that exposes a portion of the storage medium with light in
87	order to record the information on the storage medium.
88	39. The camera of claim 34, wherein the means for determining the location
89	determines the name of the location of the image.
<b>9</b> 0 <b>9</b> 1	40. The camera of claim 34, wherein the means for determining the location
<b>9</b> 1	determines the geographic coordinates of the location of the image.
<b>5</b> 2	41. A camera comprising:
<b>-93</b>	an optical lens for focusing an image onto a focal plane;
194 195 196	a storage medium for recording the image, the medium comprising film or memory cells;
<b>5</b>	a location sensing system, the system configured to record the location onto the storage
96	medium.
97	42. The camera of claim 41, wherein the location sensing system comprises a
98	cellular transceiver, the system configured to triangulate the position of the camera through
99	signals sent and/or received by the transceiver.
100	43, The camera of claim 42, wherein one or more of the signals is sent and/or
101	received over a cellular control channel.
102	44. The camera of claim 41, wherein the location sensing system comprises a
103	GPS receiver.
104	45. The camera of claim 41, wherein the camera is a video camera.
105	46. The camera of claim 1, wherein the camera is a video camera.